Principal Cumulant Component Analysis

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Blaming the math

• Wired: Gaussian copulas for CDOs.



the secret formula That Destroyed Wall Street

Ρ=φ(**A**, **B**, γ)

• NYT: normal market in VaR.



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The New York Times January 4, 2009

Risk Mismanagement

By JOE NOCERA

THERE AREN'T MANY widely told anecdotes about the current <u>financial crisis</u>, at least not yet, but there's one that made the rounds in 2007, back when the big investment banks were first starting to write down
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Why not Gaussian

• Log characteristic function

$$\log \mathsf{E}(\exp(i\langle \mathbf{t}, \mathbf{x}
angle)) = \sum_{|lpha|=1}^{\infty} i^{|lpha|} \kappa_{lpha}(\mathbf{x}) rac{\mathbf{t}^{lpha}}{lpha!}.$$

• Gaussian assumption equivalent to quadratic approximation:

$$\infty = 2.$$

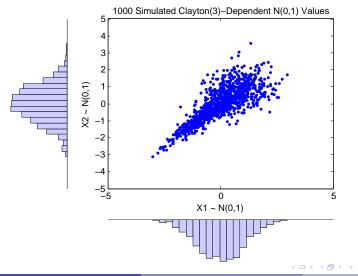
• If x is multivariate Gaussian, then

$$\log \mathsf{E}(\exp(i\langle \mathbf{t}, \mathbf{x} \rangle)) = i\langle \mathsf{E}(\mathbf{x}), \mathbf{t} \rangle + \frac{1}{2}\mathbf{t}^{\top} \operatorname{Cov}(\mathbf{x})\mathbf{t}.$$

- \$\mathcal{K}_1(\mathbf{x})\$ mean, \$\mathcal{K}_2(\mathbf{x})\$ (co)variance, \$\mathcal{K}_3(\mathbf{x})\$ (co)skewness, \$\mathcal{K}_4(\mathbf{x})\$ (co)kurtosis,...
- Non-Gaussian data: Not enough to look at just mean and covariance.

Why not copulas

- Nassim Taleb: "Anything that relies on correlation is charlatanism."
- Even if marginals normal, dependence might not be.



Why not VaR

- Paul Wilmott: "The relationship between two assets can never be captured by a single scalar quantity."
- Multivariate $f : \mathbb{R}^n \to \mathbb{R}$

$$\mathcal{F}(\mathbf{x}) = a_0 + \mathbf{a}_1^\top \mathbf{x} + \mathbf{x}^\top A_2 \mathbf{x} + \mathcal{A}_3(\mathbf{x}, \mathbf{x}, \mathbf{x}) + \cdots + \mathcal{A}_k(\mathbf{x}, \dots, \mathbf{x}) + \cdots,$$

grad $f(\mathbf{x}) \in \mathbb{R}^n$, Hess $f(\mathbf{x}) \in \mathbb{R}^{n \times n}$, ..., $D^{(k)}f(\mathbf{x}) \in \mathbb{R}^{n \times \cdots \times n}$.

• Hooke's law in 1D: x extension, F force, k spring constant,

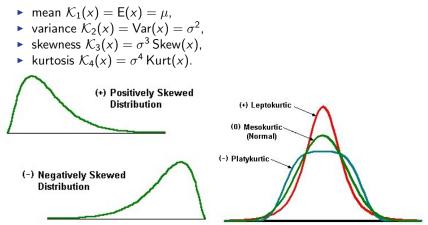
$$F = -kx$$
.

• Hooke's law in 3D: $\mathbf{x} = (x_1, x_2, x_3)$, elasticity tensor $C \in \mathbb{R}^{3 \times 3 \times 3 \times 3}$, stress $\Sigma \in \mathbb{R}^{3 \times 3}$, strain $\Gamma \in \mathbb{R}^{3 \times 3}$

$$\sigma_{ij} = \sum_{k,l=1}^{3} c_{ijkl} \gamma_{kl}.$$

Cumulants

• Univariate distribution: First four cumulants are



• **Multivariate distribution:** Covariance matrix *partly* describes the dependence structure — enough for Gaussian. Cumulants describe higher order dependence among random variables.

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Examples of cumulants

Univariate: $\mathcal{K}_p(x)$ for p = 1, 2, 3, 4 are mean, variance, skewness, kurtosis (unnormalized)

Discrete: $x \sim \text{POISSON}(\lambda)$, $\mathcal{K}_p(x) = \lambda$ for all p.

Continuous: $x \sim \text{UNIFORM}([0,1])$, $\mathcal{K}_p(x) = B_p/p$ where $B_p = p$ th Bernoulli number.

Nonexistent: $\mathbf{x} \sim \text{STUDENT}(3)$, $\mathcal{K}_{p}(\mathbf{x})$ does not exist for all $p \geq 3$. Multivariate: $\mathcal{K}_{1}(\mathbf{x}) = \mathsf{E}(\mathbf{x})$ and $\mathcal{K}_{2}(\mathbf{x}) = \text{Cov}(\mathbf{x})$. Discrete: $\mathbf{x} \sim \text{MULTINOMIAL}(n, \mathbf{q})$, $\kappa_{j_{1}\cdots j_{p}}(\mathbf{x}) = n \frac{\partial^{p}}{\partial t_{j_{1}}\cdots \partial t_{j_{p}}} \log(q_{1}e^{t_{1}x_{1}} + \cdots + q_{k}e^{t_{k}x_{k}})\Big|_{t_{1},\dots,t_{k}=0}$.

Continuous: $\mathbf{x} \sim \text{NORMAL}(\boldsymbol{\mu}, \boldsymbol{\Sigma})$, $\mathcal{K}_p(\mathbf{x}) = 0$ for all $p \geq 3$.

Tensors as hypermatrices

• Choose bases, ignore contra/covariance, write $\mathbf{A} \in U \otimes V \otimes W$ as

$$\mathcal{A} = \llbracket a_{ijk} \rrbracket_{i,j,k=1}^{l,m,n} \in \mathbb{R}^{l \times m \times n}$$

• Matrix rank. $A \in \mathbb{R}^{m \times n}$.

$$\mathsf{rank}(A) = \min\{r \mid A = \sum_{i=1}^{r} \mathbf{u}_i \mathbf{v}_i^{\top}\} \\ = \dim(\mathsf{span}_{\mathbb{R}}\{A_{\bullet 1}, \dots, A_{\bullet n}\}) = \dim(\mathsf{span}_{\mathbb{R}}\{A_{1\bullet}, \dots, A_{m\bullet}\}).$$

• Tensor rank.
$$\mathcal{A} \in \mathbb{R}^{l imes m imes n}$$

• outer-product rank: $\mathbf{u} \otimes \mathbf{v} \otimes \mathbf{w} := \llbracket u_i v_j w_k \rrbracket_{i,j,k=1}^{l,m,n}$,

$$\operatorname{rank}_{\otimes}(\mathcal{A}) = \min\{r \mid \mathcal{A} = \sum_{i=1}^{r} \mathbf{u}_i \otimes \mathbf{v}_i \otimes \mathbf{w}_i\};$$

multilinear rank: generalizes row and column ranks,

$$\mathsf{rank}_{\boxplus}(\mathcal{A}) = (r_1(\mathcal{A}), r_2(\mathcal{A}), r_3(\mathcal{A})).$$

Generalizing A = UΣV^T = Σ^r_{i=1}σ_i**u**_i ⊗ **v**_i: either keep Σ diagonal or U, V orthonormal but not both.

Humans cannot understand 'raw' tensors

Humans cannot make sense out of more than O(n) numbers. For most people, $5 \le n \le 9$ [Miller; '56].

- VaR: single number
 - Readily understandable.
 - Not sufficiently informative and discriminative.
- Covariance matrix: $O(n^2)$ numbers
 - Hard to make sense of without further processing.
 - Eigenvalue decomposition: PCA, MDS, ISOMAP, LLE, Laplacian Eigenmap, etc.
- Cumulant of order $d: O(n^d)$ numbers
 - How to make sense of these?
 - Want analogue of 'eigenvalue decomposition' for symmetric tensors.

SVD for tensors

• Linear combination of decomposable tensors

$$\mathcal{A} = (X, Y, Z) \cdot \Sigma = \sum_{i=1}^{r} \sigma_i \mathbf{x}_i \otimes \mathbf{y}_i \otimes \mathbf{z}_i.$$

- Computational complexity: Strassen matrix multiplication/inversion $\inf \{ \omega \mid \operatorname{rank}_{\otimes} \left(\sum_{i,i,k=1}^{n} \varphi_{ik} \otimes \varphi_{kj} \otimes E_{ij} \right) = O(n^{\omega}) \} = 2?$
- Quantum computing: algebraic measure of entanglement

 $|\mathsf{GHZ}\rangle = |0\rangle \otimes |0\rangle \otimes |0\rangle + |1\rangle \otimes |1\rangle \otimes |1\rangle \in \mathbb{C}^{2\times 2\times 2}.$

- Geometry: secant varieties of Segre and Veronese varieties.
- Multilinear combination of orthonormal U, V, W

$$\mathcal{A} = (U, V, W) \cdot \mathcal{C} = \sum_{i,j,k=1}^{r_1, r_2, r_3} c_{ijk} \mathbf{u}_i \otimes \mathbf{v}_j \otimes \mathbf{w}_k.$$

• **Geometry:** subspace varieties, symmetric subspace varieties $\operatorname{Gr}(I,p) \times \operatorname{Gr}(m,q) \times \operatorname{Gr}(n,r) \times \mathbb{R}^{p \times q \times r} \to \operatorname{Sub}_{p,q,r}(\mathbb{R}^{I},\mathbb{R}^{m},\mathbb{R}^{n}).$

Eliminating the impossible

- Computing 3-tensor rank is NP hard [Håstad; 1990].
- Just about every tensor problem is NP hard in both the Cook-Karp-Levin and the Blum-Shub-Smale sense [L & Hillar; 2009]:
 - best rank-1 approximation of a 3-tensor;
 - best rank-1 approximation of a symmetric 3-tensor;
 - singular values/vectors of a 3-tensor [L; 2005];
 - eigenvalues/vectors of a symmetric 3-tensor [L; 2005], [Qi; 2005];
 - spectral norm of a 3-tensor;
 - feasibility of a system of bilinear equations;
 - solving a system of bilinear equations in both the exact and least squares sense.
- Best rank-r tensor approximation problems are unsolvable in general [de Silva & L; 2008], [Comon, Golub, L, Mourrain; 2008].

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Among whatever remains

- **Principal Component Analysis:** components accounting for variation in covariance.
- Principal Cumulant Component Analysis: components accounting for variation in all cumulants simultaneously [L & Morton; 2008], [Morton & L; 2009],

$$\min_{Q \in \mathcal{O}(n,r), \ \mathcal{C}_{p} \in \mathcal{S}^{p}(\mathbb{R}^{r})} \sum_{p=1}^{\infty} \alpha_{p} \| \hat{\mathcal{K}}_{p}(\mathbf{y}) - (Q, \ldots, Q) \cdot \mathcal{C}_{p} \|_{F}^{2}.$$

• Surprising relaxation: optimization over a single Grassmannian Gr(n, r) of dimension r(n - r),

$$\max_{\boldsymbol{Q}\in\mathsf{Gr}(\boldsymbol{n},\boldsymbol{r})}\sum_{p=1}^{\infty}\alpha_{p}\|(\boldsymbol{Q}^{\top},\ldots,\boldsymbol{Q}^{\top})\cdot\hat{\mathcal{K}}_{p}(\mathbf{y})\|_{F}^{2}.$$

• Efficient algorithm exists: limited memory BFGS on Grassmannian [Savas & L; 2009].

Properties of cumulants

Multilinearity: If **x** is a \mathbb{R}^n -valued random variable and $A \in \mathbb{R}^{m \times n}$

$$\mathcal{K}_{p}(A\mathbf{x}) = (A, \ldots, A) \cdot \mathcal{K}_{p}(\mathbf{x}).$$

Additivity: If $\mathbf{x}_1, \ldots, \mathbf{x}_k$ are mutually independent of $\mathbf{y}_1, \ldots, \mathbf{y}_k$, then

$$\mathcal{K}_{\rho}(\mathbf{x}_1 + \mathbf{y}_1, \dots, \mathbf{x}_k + \mathbf{y}_k) = \mathcal{K}_{\rho}(\mathbf{x}_1, \dots, \mathbf{x}_k) + \mathcal{K}_{\rho}(\mathbf{y}_1, \dots, \mathbf{y}_k).$$

Independence: If I and J partition $\{j_1, \ldots, j_p\}$ so that \mathbf{x}_I and \mathbf{x}_J are independent, then

$$\kappa_{j_1\cdots j_p}(\mathbf{x})=0.$$

Support: There are no distributions where

$$\mathcal{K}_p(\mathbf{x}) egin{cases}
eq 0 & 3 \leq p \leq n, \\
eq 0 & p > n. \end{cases}$$

Principal and independent component analysis

Linear generative model:

$$\mathbf{y} = A\mathbf{s} + \boldsymbol{\varepsilon}.$$

Principal component analysis: s Gaussian,

$$\hat{\mathcal{K}}_2(\mathbf{y}) = Q \Lambda_2 Q^\top = (Q, Q) \cdot \Lambda_2,$$

 $\Lambda_2 \approx \hat{\mathcal{K}}_2(\mathbf{s})$ diagonal matrix, $Q \in O(n, r)$, [Pearson; 1901]. Independent component analysis: \mathbf{s} statistically independent entries, ε Gaussian

$$\hat{\mathcal{K}}_{p}(\mathbf{y}) = (Q, \ldots, Q) \cdot \Lambda_{p}, \quad p = 2, 3, \ldots,$$

 $\Lambda_{
ho} pprox \hat{\mathcal{K}}_{
ho}(\mathbf{s})$ diagonal tensor, $Q \in \mathrm{O}(n,r)$, [Comon; 1994].

Principal cumulant component analysis

• Note that if $oldsymbol{arepsilon} = oldsymbol{0}$, then

$$\mathcal{K}_p(\mathbf{y}) = \mathcal{K}_p(Q\mathbf{s}) = (Q, \ldots, Q) \cdot \mathcal{K}_p(\mathbf{s}).$$

 In general, want principal components that account for variation in all cumulants simultaneously

$$\min_{Q\in \mathsf{O}(n,r), \, \mathcal{C}_{p}\in\mathsf{S}^{p}(\mathbb{R}^{r})} \sum_{p=1}^{\infty} \alpha_{p} \|\hat{\mathcal{K}}_{p}(\mathbf{y}) - (Q, \ldots, Q) \cdot \mathcal{C}_{p}\|_{F}^{2},$$

• We have assumed $A = Q \in O(n, r)$ since otherwise A = QR and

$$\mathcal{K}_{\rho}(A\mathbf{s}) = (Q, \ldots, Q) \cdot [(R, \ldots, R) \cdot \mathcal{K}_{\rho}(\mathbf{s})].$$

Recover orthonormal basis of subspace spanned by A.
C_p ≈ (R,..., R) · K̂_p(s) not necessarily diagonal.

Newton/quasi-Newton on a Grassmannian

- Objective $\Phi : \operatorname{Gr}(n, r) \to \mathbb{R}$.
- T_X tangent space at $X \in Gr(n, r)$

$$\mathbb{R}^{n\times r}\ni\Delta\in\mathsf{T}_X\qquad\Longleftrightarrow\qquad\Delta^\top X=0$$

- **1** Compute Grassmann gradient $\nabla \Phi \in \mathbf{T}_X$.
- Ompute Hessian or update Hessian approximation

$$H: \Delta \in \mathbf{T}_X \to H\Delta \in \mathbf{T}_X.$$

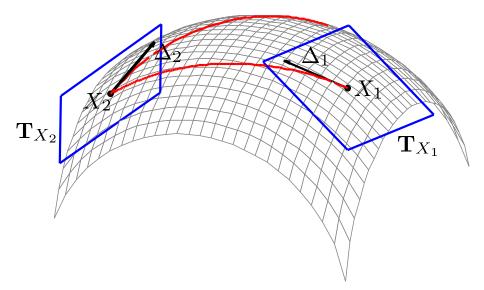
3 At
$$X \in Gr(n, r)$$
, solve

$$H\Delta = -\nabla \Phi$$

for search direction Δ .

- Update iterate X: Move along geodesic from X in the direction given by Δ.
- [Arias, Edelman, Smith; 1999], [Savas & L.; 2009].

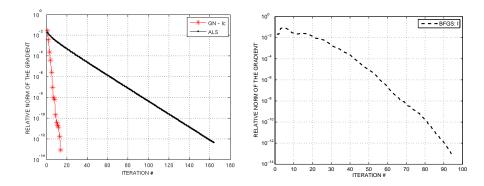
Picture



Convergence

Left: $||(X, X, X) \cdot S_3||^2$. Compares favorably with Alternating Least Squares.

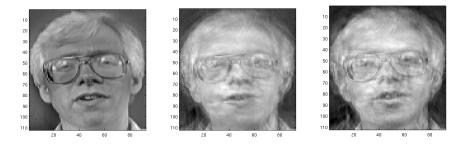
Right: $\frac{1}{2!} \| (X, X) \cdot S_2 \|^2 + \frac{1}{3!} \| (X, X, X) \cdot S_3 \|^2 + \frac{1}{4!} \| (X, X, X, X) \cdot S_4 \|^2$.



Skew eigenfaces

Left: Original. Center: 30 variance eigenvectors.

Right: 20 variance eigenvectors and 10 skewness eigenvectors.



Higher order portfolio optimization

$$\min \sum_{d=2}^{n} \alpha_d(\mathbf{x}^{\top}, \dots, \mathbf{x}^{\top}) \cdot \mathcal{K}_d(\mathbf{y}) \quad \text{s.t.} \quad \mathbf{x}^{\top} \mathsf{E}(\mathbf{y}) > \underline{r}.$$

• n = 2: Markowitz mean-variance optimal portfolio theory.

• n = 4: mean-variance-skewness-kurtosis optimal portfolio theory.

