$\ldots, N\}$. The simplest case where $q_{k}$ consists of a block of contiguous carriers (i.e., $q_{k}=\{j+(k-1) N / V \mid j=1, \ldots, N / V \in\}$ ), which is especially suitable for differential detection systems [1]. Blocks may contain non-contiguous carriers for better PF reduction capability at the cost of extra complexity [3]. Let $\phi_{k}, k=1, \ldots, V$, be a set of phases with $\phi_{1}=0$. The modified symbols $\tilde{c}_{j}=c e^{i \phi k}$ for $j \in$ $q_{k}$ and $\tilde{c}=\left[\tilde{c}_{1}, \tilde{c}_{2}, \ldots, \tilde{c}_{n}\right]$. For a given information vector $\underline{c}$, the reported optimisation criterion is [1]

$$
\begin{equation*}
\left[\hat{\phi}_{2}, \hat{\phi}_{3}, \ldots, \hat{\phi}_{V}\right]=\underset{\left[\phi_{2}, \phi_{3}, \ldots, \phi_{V}\right]}{\operatorname{argmin}}\|A \tilde{c}\|_{\infty} \tag{4}
\end{equation*}
$$

Then, the actual transmitted sequence is given by eqn. 3 with this set of block phase factors ( $\underline{c}$ replaced by $\underline{\tilde{c}}$ ), which may have to be transmitted by some means (e.g. on extra carriers). To reduce the search complexity, each $\phi_{k}$ is discrete and takes a value from the set $\phi_{k} \in\{0, \pi / 2, \pi, 3 \pi / 2\}$.

Fig. 1 shows the distribution of the PF for the uncoded case (i.e. there is no attempt to reduce the peak factor) and for a PTS with four blocks. Several observations can be made:
(i) For the uncoded case, the LPF follows the Rayleigh distribution. However, the TPF is $\sim 0.5 \mathrm{~dB}$ worse than that predicted by the Rayleigh distribution.
(ii) The use of the TPF results in an estimated PF reduction of only 1 dB for the PTS scheme.
(iii) The use of the LPF results in an estimated PF reduction of 4 dB for the PTS scheme.
Therefore, at least in this case, the PTS gains reported [1] appear to be optimistic. Note that the difference between the TPF and the LPF is $\sim 3 \mathrm{~dB}$ (Fig. 1). The reason seems to be the following: since eqn. 4 is equivalent to suppressing $|s(k T)|$ for $k=0, \ldots, N-1$ while keeping the area under $|s(t)|^{2}$ constant, this very fact causes the true peak of $|s(t)|$ to move away from the sampling points.


Fig. 1 Probability that peak factor $\gamma$ exceeds $\alpha$ for 128 QPSK-modulated carriers
TPF: true peak factor LPF: lower peak factor UNC: uncoded Optimisation criterion eqn. $4,10^{6}$ simulation points
—— TPF for PTS
.-. - Rayleigh
--- LPF for PTS
$\cdots \cdot$ TPF for UNC
$\times \times \times$ LPF for UNC

In fact, eqn. 4 is not the only possible optimisation criterion. A recent Letter [4] shows that a bound on the PF can obtained by the sum of the autocorrelation (aperiodic) sidelobe magnitudes of the modulation symbol sequence. This suggests another optimisation criterion. Let $\rho(k)$ be the aperiodic autocorrelation of $\underline{\tilde{c}}$. Then, for a given information vector $\underline{c}$, the new optimisation criterion is

$$
\begin{equation*}
\left[\hat{\phi}_{2}, \hat{\phi}_{3}, \ldots, \hat{\phi}_{V}\right]=\underset{\left[\phi_{2}, \phi_{3}, \ldots, \phi_{V}\right]}{\operatorname{argmin}} \sum_{k=1}^{N-1}|p(k)| \tag{5}
\end{equation*}
$$

Fig. 2 shows the PF distribution with the use of eqn. 5. A PF reduction of $\sim 2.5 \mathrm{~dB}$ can be achieved at $\operatorname{Pr}(\gamma>\alpha)=10^{-5}$. Note that the difference between the TPF and the LPF is 0.5 dB in this case (Fig. 2). Since the sum in eqn. 5 determines a bound on the true peak, its minimisation leads to a flatter $|s(t)|$ for $0 \leq t<\tau$, not just
on the sampling points. In a practical system, implementing eqn. 5 can be too complicated. For QPSK, the real and imaginary part of each $\rho(k)$ can be obtained without any multiplications the number of integer additions is in the order of $N^{2}$ ). So the total complexity varies as $O\left(4^{v-1} N^{2}\right)$.


Fig. 2 Probability that peak factor $\gamma$ exceeds $\alpha$ for 128 QPSK-modulated carriers
Optimisation criterion eqn. $5,10^{6}$ simulation points - TPF for PTS

- LPF for PTS

Conclusions: The PTS approach requires that we determine several block phase factors, for which a new optimisation criterion has been presented. Assuming an ideal anti-aliasing filter, the output signal closely resembles the multicarrier signal (eqn. 1). Therefore, it is not sufficient to find the PF on the basis of $N$ samples. The reported gains of PTS with eqn. 4 appear to be optimistic, however, it may be that the use of a raised-cosine filter alleviates this problem.
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## Security of the Cao-Li public key cryptosystem

Lim Lek Heng

The author shows that the Cao-Li cryptosystem proposed in [1] is not secure. Its private key can be reconstructed from its public key using elementary means such as LU-decomposition and the Euclidean algorithm.

Description of cryptosystem: The Cao-Li public key cryptosystem was first proposed in [1]. It encrypts messages using a bilinear form that is chosen to permit easy decryption by the Chinese remainder theorem. Public key cryptosystems that are designed
along this line are not uncommon in the Chinese cryptographic literature. However, as most of the original papers were published in Chinese, they remained relatively obscure until a few of them were described in [2] (in English) recently. Our description below is based on the latter reference.
Let $p_{1}, \ldots, p_{n}$ be $n$ distinct primes where $p_{i} \equiv 3 \bmod 4$. For $i=1$, $\ldots, n$, define

$$
m_{i}:=\frac{1}{p_{i}}\left(\prod_{j=1}^{n} p_{j}\right)
$$

Compute for each $m_{i}$, an integer $m_{i}^{\prime}$ that satisfies $m_{i}^{\prime} m_{i} \equiv 1 \bmod p_{i}$ and $0<m_{i}^{\prime}<p_{i}$. We define positive integers

$$
\lambda_{i}:=m_{i}^{\prime} m_{i}
$$

for $i=1, \ldots, n$ and the diagonal matrix

$$
\Lambda:=\operatorname{diag}\left[\lambda_{1}, \ldots, \lambda_{n}\right]
$$

Note that

$$
\begin{equation*}
\lambda_{i} \equiv \delta_{i j} \bmod p_{j} \tag{1}
\end{equation*}
$$

where $\delta_{i j}$ is 1 if $i=j$ and 0 otherwise.
We choose another two invertible $n \times n$ lower-triangular matrices $P_{1}$ and $P_{2}$ with non-negative integer entries that are bounded by

$$
\begin{equation*}
\beta:=\min _{1 \leq i \leq n} \sqrt{\frac{p_{i}}{i(i+1) d}} \tag{2}
\end{equation*}
$$

where $d \geq 1$ is a chosen positive integer.
The secret key comprises the two matrices $P_{1}, P_{2}$ and the primes $p_{i}, i=1, \ldots, n$. The public key is the $n \times n$ symmetric matrix $B$ given by

$$
B:=P_{2}^{T} P_{1}^{T} \Lambda P_{1} P_{2}
$$

Let the message block be $\mathbf{x}=\left(x_{1}, \ldots, x_{n}\right)$ where $0 \leq x_{i} \leq d$. The ciphertext $y$ is computed as

$$
y=\mathrm{x} B \mathrm{x}^{T}
$$

If we let $\mathbf{z}:=\mathbf{x} P_{2}{ }^{T} P_{1}{ }^{T}$, then

$$
y=\mathbf{z} \Lambda \mathbf{z}^{T}=\lambda_{1} z_{1}^{2}+\cdots+\lambda_{n} z_{n}^{2}
$$

From eqn. 1, we have

$$
\begin{equation*}
z_{k}^{2} \equiv y \bmod p_{k} \tag{3}
\end{equation*}
$$

Keeping in mind that $P_{1}{ }^{T}$ and $P_{2}{ }^{T}$ are upper-triangular and their entries are non-negative and bounded by $\beta$, we have, from eqn. 2 and $0 \leq x_{i} \leq d$, that

$$
\begin{equation*}
0 \leq z_{k} \leq \sum_{i=1}^{k} \sum_{j=i}^{k} d \beta^{2}=d \beta^{2} \frac{k(k+1)}{2}<\frac{p_{k}}{2} \tag{4}
\end{equation*}
$$

We can carry out decryption as follows. For each $k=1, \ldots, n$, compute the unique $z_{k}$ satisfying eqns 3 and 4 . The message can then be recovered by

$$
\begin{equation*}
\mathbf{x}=\mathbf{z}\left(P_{2}^{T} P_{1}^{T}\right)^{-1} \tag{5}
\end{equation*}
$$

Note that since $p_{k} \equiv 3 \bmod 4$, effective algorithms for computing square roots mod $p_{k}$ exist (see [3]).

Key recovery: We will first recover $\Lambda$ from $B$. Let $P_{1} P_{2}=: P=$ $\left(p_{i j}\right)_{1 \leq i, j \leqslant n}$. Then $P$ is an invertible lower-triangular matrix with non-negative integral entries by the same properties of $P_{1}$ and $P_{2}$. Since $P$ is invertible and has non-negative integral entries, we have $\operatorname{det} P=1$. Moreover, we also have $\operatorname{det} P=p_{11} \times \ldots \times p_{n n}$ since $P$ is triangular. As all the $P_{i i}$ values are non-negative, it then follows that $p_{i i}=1$ for $i=1, \ldots, n$.
$\Lambda$ and $P$ can be recovered from $B$ using an algorithm that is very similar to the algorithm for $L U$-decomposition of a matrix (the difference being that row reduction is done starting from the bottom rows). Denote the $i$ th row of $B$ by $\mathbf{b}_{i}=\left(b_{i}, \ldots, b_{i n}\right), i=1$, $\ldots, n$. We know immediately that $b_{n n}=\lambda_{n}$. Table 1 shows algorithm A .

The following shows that algorithm $A$ indeed yields the required output. Let the $i$ th row of $P$ be $\mathbf{p}_{i}, i=1, \ldots, n$. Since $p_{i i}=$ 0 if $j<i$ and $p_{i i}=1$, we may write $\mathbf{b}_{i}=\lambda_{i} \mathbf{p}_{i}+\sum_{j=i+1}^{n} \lambda_{j} p_{j i} \mathbf{p}_{j}$. For each $i=n-1, n-2, \ldots, 1$, the inner loop of step 1 effectively carries out the following:

$$
\mathbf{b}_{i} \leftarrow \mathbf{b}_{i}-\sum_{j=i+1}^{n} \frac{b_{j i}}{b_{j j}} \mathbf{b}_{j}
$$

Table 1: Algorithm A

| Algorithm A |  |
| :--- | :--- |
| Input $\quad B=\left(\mathbf{b}_{1}, \ldots, \mathbf{b}_{n}\right)^{T}=\left(b_{i j}\right)_{1 \leq i, j \leq n}$ |  |
| Output $\quad \lambda_{1}, \ldots, \lambda_{n}, P$ |  |
| Step 1 $\quad$ for $i=n-1, n-2, \ldots, 1$ do |  |
|  | for $j=n, n-1, \ldots, i+1$ do |
|  | $\mathbf{b}_{i} \leftarrow \mathbf{b}_{i}-\frac{b_{j i}}{b_{j j}} \mathbf{b}_{j ;} ;$ |
|  | end; |
|  | end; |
| Step 2 | for $i=1, \ldots, n$ do |
|  | $\lambda_{i} \leftarrow b_{i i} ;$ |
| $\mathbf{b}_{i} \leftarrow \mathbf{b}_{i} / \lambda_{i} ;$ |  |
|  | $P \leftarrow B$ |
|  |  |

We shall show inductively that $\mathbf{b}_{i}$ is reduced to $\lambda_{i} \mathbf{p}_{i}$ at stage $i$ : clearly $\mathbf{b}_{n}=\lambda_{n} \mathbf{p}_{n} ;$ suppose $\mathbf{b}_{i}$ is reduced to $\lambda_{i} \mathbf{p}_{i}$ at stage $i=n-1, \ldots$, $n-k$, then at stage $n-k-1$ :

$$
\begin{aligned}
\mathbf{b}_{n-k-1} & \leftarrow \mathbf{b}_{n-k-1}-\sum_{j=n-k}^{n} \frac{b_{j i}}{b_{j j}} \mathbf{b}_{j} \\
& =\mathbf{b}_{n-k-1}-\sum_{j=n-k}^{n} \lambda_{j} p_{j i} \mathbf{p}_{j} \\
& =\lambda_{n-k-1} \mathbf{p}_{n-k-1}
\end{aligned}
$$

Hence, step 1 reduces $B=\left(\mathbf{b}_{1}, \ldots, \mathbf{b}_{n}\right)^{T}$ to $\left(\lambda_{n} \mathbf{p}_{n}, \ldots, \lambda_{n} \mathbf{p}_{n}\right)^{T}=\Lambda P$. Since the diagonal entries of $P$ are all ones, the diagonal entries of $\Lambda P$ are the required $\lambda_{i}$ values. Consequently, $P$ can be recovered by dividing each row by its corresponding diagonal entry.

We can now recover the moduli $p_{1}, \ldots, p_{n}$ from $\lambda_{1}, \ldots, \lambda_{n}$. From eqn. 1 , we see that, for a fixed $i, p_{i} \mid \lambda_{j}$ for all $j \neq i$ and $p_{i} \mid \lambda_{i}-1$. Hence

$$
p_{i} \mid d_{i}:=\operatorname{gcd}\left(\lambda_{1}, \ldots, \lambda_{i-1}, \lambda_{i}-1, \lambda_{i+1}, \ldots, \lambda_{n}\right)
$$

It could of course happen that $d_{i} \neq p_{i}$ for some $i$. Hence, this process only partially recovers the $p_{i}$ values. However, our computer simulations (using C ++ with LiDIA) show that instances where $d_{i}$ $\neq p_{i}$, are rare. We shall give some heuristics to substantiate this claim. For $d_{i}=p_{i}$, it is sufficient that $\operatorname{gcd}\left(m_{1}^{\prime}, \ldots, m_{i-1}^{\prime}, m_{i+1}^{\prime}, \ldots\right.$, $\left.m_{n}^{\prime}\right)=1$. From [4], we have

$$
\begin{aligned}
\#\left\{\left(a_{1}, \ldots, a_{k}\right)\right. & \left.\in \mathbb{N}^{k} \operatorname{lgcd}\left(a_{1}, \ldots, a_{k}\right)=1, \text { all } a_{i} \leq N\right\} \\
& = \begin{cases}N^{k} / \zeta(k)+O\left(N^{k-1}\right) & \text { if } k>2 \\
6 N^{2} / \pi^{2}+O(N \log N) & \text { if } k=2\end{cases}
\end{aligned}
$$

where $\zeta(s)=\sum_{i=1}^{\infty} i^{-s}$ the Riemann zeta function. Assuming that each $m_{i}^{\prime}$ is randomly distributed in $\{1, \ldots, N\}$ where $N:=\max \left\{p_{1}\right.$, $\left.\ldots, p_{n}\right\}$, the probability that $\operatorname{gcd}\left(m_{1}^{\prime}, \ldots, m_{i-1}^{\prime}, m_{i+1}^{\prime}, \ldots, m_{n}^{\prime}\right)=1$ is then at least $\zeta(n-1) \geqq 6 / \pi^{2} \simeq 0.60$ when $N$ is large enough. So we can expect to recover more than half of the $p_{i}$ values. In fact, our simulations show that we almost always have $d_{i}=p_{i}$ and many of the rare exceptions are of the form $d_{i}=2 p_{i}$, where $p_{i}$ can also be recovered easily.

Conclusion: Note that algorithm A is essentially $L U$-decomposition and the $d_{i}$ values can be computed using the Euclidean algorithm. Since these two methods can be carried out efficiently, we can easily recover $P$ and most of the $p_{i}$ values. It then follows that the Cao-Li cryptosystem is insecure and thus should not be used.

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## Asynchronous analogue-to-digital converter for single-electron circuits

Su Jin Ahn and Dae Mann Kim

An analogue-to-digital conversion scheme based on the $e$-periodic transfer characteristics of an SET inverter is proposed. The authors demonstrate the 4 bit analogue-to-digital converter performance using Monte-Carlo simulation in which an SET inverter implements a binary quantiser and encoder for one significant bit. This scheme can be easily extended to higher order bits.

Introduction: The rapid progress in nanofabrication technologies have led to the discovery of a novel, single-electron tunnelling device. Since operation of a single-electron device is based on the Coulomb blockade phenomenon [1] emphasised in nanoscaledevices, single-electron transistors (SETs) have their own distinct features such as their inherent stochastic [3] and e-periodic output transfer characteristics. We propose an analogue-to-digital converter (ADC) architecture using the SET inverter's periodic output nature instead of directly imitating the method used in VLSI circuits by replacing FETs by SETs. In the proposed circuit, composed of a switch and voltage ramps supplied from the conventional VLSI circuitry and SET inverters, the analogue input signal is represented by modulated digital pulses coded by pulsewidth modulation (PWM), i.e. the magnitude of the analogue signal is represented by the duration of the pulse, and the digital output signal has a voltage of either 0 V or $V_{d d}$, depending on its logical state ' 0 ' or ' 1 ', respectively. In this Letter, we have demonstrated a 4 bit ADC using numerical simulation and have also examined the possibility of extending an $N$ bit ADC .


Fig. 1 Proposed SET inverter circuit

Principle of operation: The principle part of an asynchronous ADC circuit is an SET inverter modified from that by Tucker in [2], as shown in Fig. 1. The set of capacitance parameters used in Fig. 1 is

$$
\begin{align*}
& C_{1}=C_{2}=1 a F \quad C_{g}=2 a F \quad C_{b}=7 a F \\
& C_{L}=24 a F=\frac{e}{V_{d d}} \quad V_{d d}=0.007 V \tag{1}
\end{align*}
$$

Fig. 2 shows the inverter's transfer characteristics based on the stability diagram for both $n$ and $p$ SETs with extended gate voltage range over $V_{d d}$.
Since each $n$ and $p$ SET has a periodic output nature of gate voltage periodicity, $\Delta V_{g}=e / C_{g}$, the inverter's output follows trace A in Fig. 2 repeatedly, with the same periodicity $\Delta V_{g}$ as for an upward gate voltage sweep. We can expect almost $50 \%$ duty-cycle square wave-like signals as an output when we apply a voltage ramp $V_{r}(t)$ to the gate of the inverter quasistatically. It is noted that our inverter resulted in almost $50 \%$ duty-cycle square wavelike signals for both rising and falling gate voltage ramps, while Tucker's resulted in $<50 \%$ and $>50 \%$ duty-cycle square wave-
like signals for rising and falling gate voltage ramps, respectively. When the voltage ramp signal is applied to the inverter, the net charge at the load capacitor $C_{L}$ oscillates from 0 to $e$ and the net charge of the centre island of $n$ and $p$ SET is added up by $-e$ per gate voltage increment of $\Delta V_{g}$. To eliminate the nonlinearity occurring from the input offset voltage $V_{\text {offset }}$ shown in Fig. 2, voltage ramp signals start not from 0 V , but from $V_{\text {ofsset }}$. In addition, by varying the slopes of the voltage ramps, we can obtain several square wavelike outputs with various frequencies $S_{i} / \Delta V_{g}$ to the time-axis, where $S_{i}$ is the slope of a voltage ramp.


Fig. 2 Output stability diagram of inverter consists of $n$ and $p$ SET stability diagram

[150/3]
Fig. 3 Schematic view of proposed ADC circuit with input signal representation and applied voltage ramp characteristics
a Proposed circuit
$b$ Input signal
$c$ Voltage ramp characteristics

Fig. 3 shows the schematic view of the resulting 4 bit ADC architecture in which a single stage consists of a voltage ramp and a SET inverter.

As an analogue input signal coded by PWM is applied to the switch, voltage ramps start to rise from $V_{\text {offset }}$ during the duration of pulse (switch ON time) with various speeds of their own, and then the output of each bit, either 0 V or $V_{d d}$, is measured at time $T_{i n}$. The ramping slope of LSB is determined by $S_{0}=\Delta V_{g} / 2 t_{\text {unit }}$, according to the input signal resolution of $t_{\text {uni. }}$. The slope of $i$ th bit voltage ramp $S_{i}$ is automatically determined to one $2^{\text {th }}$ th of $S_{0}$.

Simulation results: We simulated the proposed circuit using a Monte-Carlo simulator called SIMON [4]. The gate voltage periodicity can be calculated to 0.08 V . The slope of the voltage ramp $S_{0}$ is selected to be $0.08 / 20 \mathrm{~ns}$ and thus the resolution of the input signal is 10 ns . Fig. 4 shows the simulation results of the proposed 4 bit ADC under the assumption of zero temperature and co-tunnelling probability for simplicity. The bits deviate from an ideal

